## Shared Autonomous Vehicle System in Residential Suburban Areas

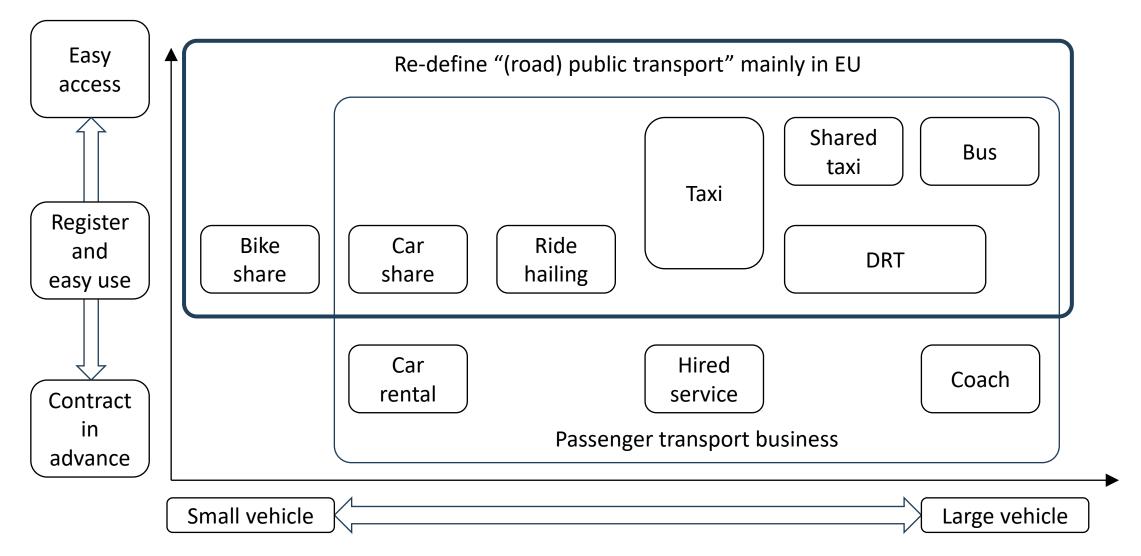
Yefang Zhou, Hitomi Sato and Toshiyuki Yamamoto Nagoya University

#### **Introduction to Case Study of Smart City**

#### Kasugai City

<u>https://www.jasca2021.jp/practices/area/japan/#case321</u>

#### From Public Transport to Transport for Public

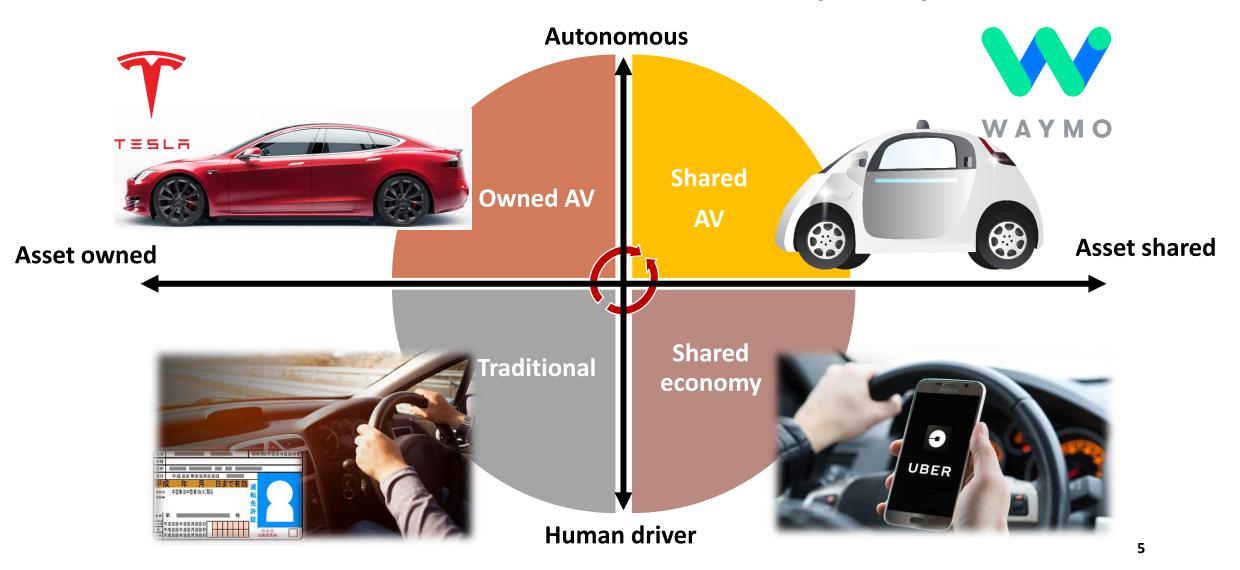




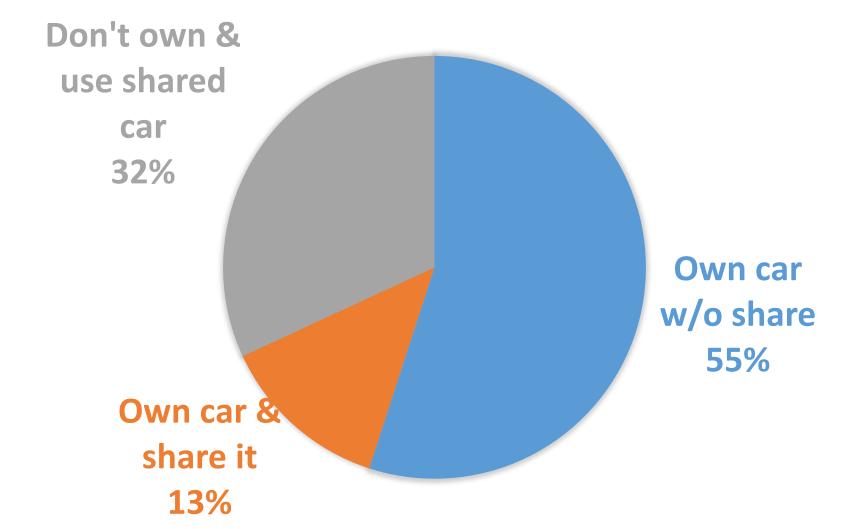


"Connected, Autonomous, Shared, Electric: Each of these has the power to turn our entire industry upside down. But the true revolution is in combining them in a comprehensive, seamless package." by Dr. Dieter Zetsche (Chairman of the Board of Management of Daimler AG)

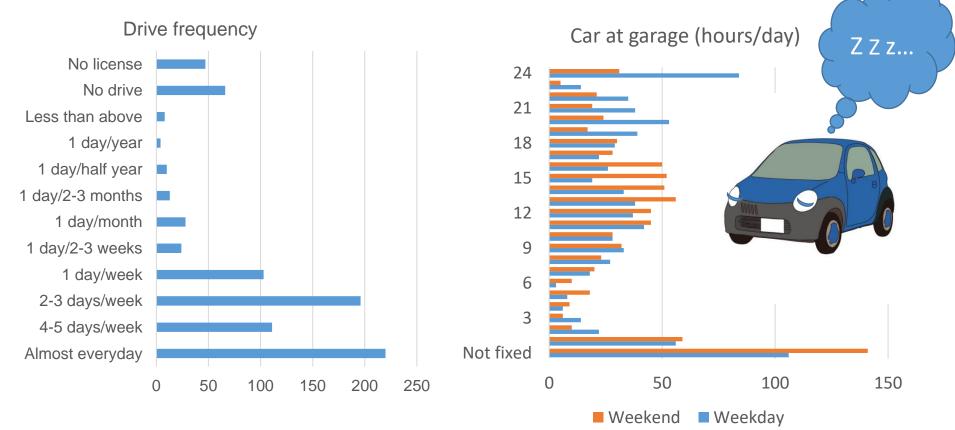
#### Shared Autonomous Vehicle (SAV)



## Intention for autonomous vehicle ownership & shared use (N=803)



### Current car use (or non-use)



- 14 & 13 hrs. at garage on weekday and weekend on average
- 10% & 14% of households don't use car on weekday and weekend

### Motorization, suburbanization and ageing

Automobiles:

- widely spread & increasing
- become daily necessities
- $\rightarrow$ dependency on automobile

Land use:

- population central  $\rightarrow$  suburbs
- suburban sprawl
- →inefficient public transit service



Mobility poor at suburban area

#### Focus

- 1. combination of P&R and AV in suburbs
  - $P\&R \rightarrow$  offer sustainable mobility service in suburbs
  - mass transportation megacities  $\rightarrow$  solid fundamental
- 2. mobility challenged people (aka, transportation poor in Japan)
  - AV  $\rightarrow$  high safety, convenience

## Proposed SAV System

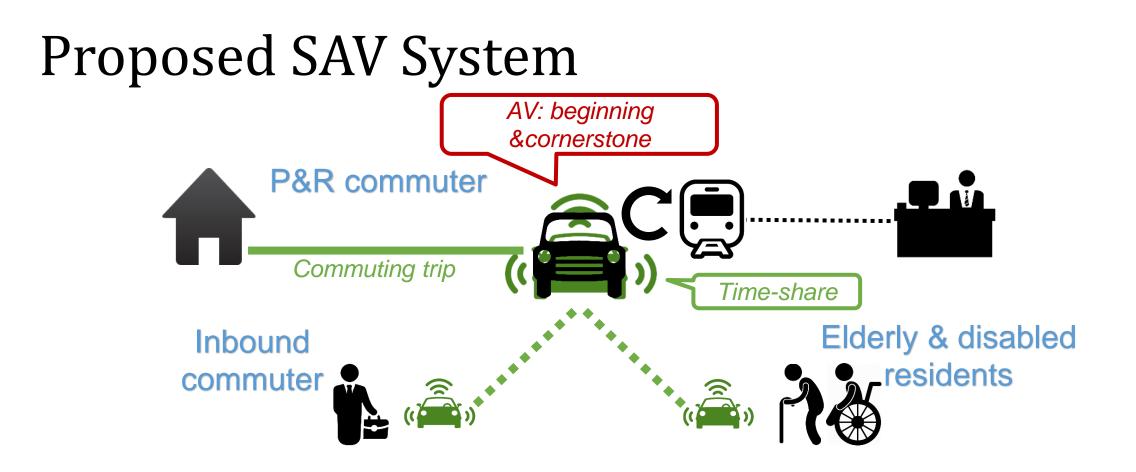
#### 3 Groups:

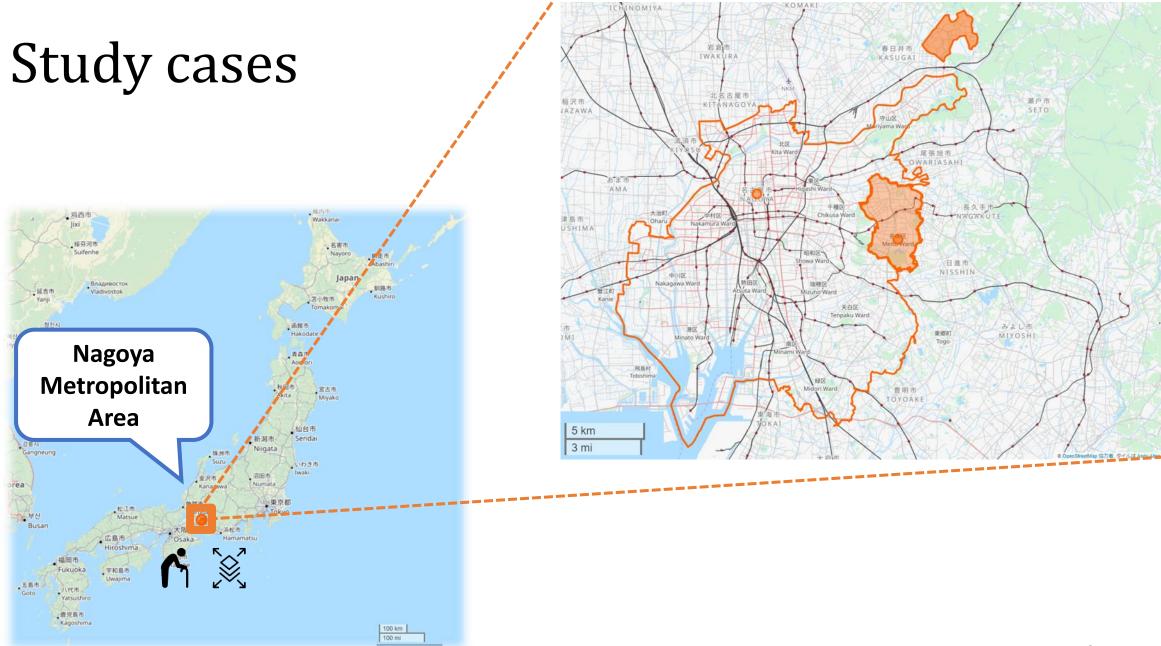
- 1. Park & Ride commuter
  - <u>Transfer at selected stations</u>
  - Depart out of target areas
  - Access mode private vehicle
- 2. Inbound commuter
  - Destination within target areas
  - Egress mode private vehicle
- 3. Elderly & disabled residents
  - Residents within target areas
  - Mobility difficulties
  - Age over 70



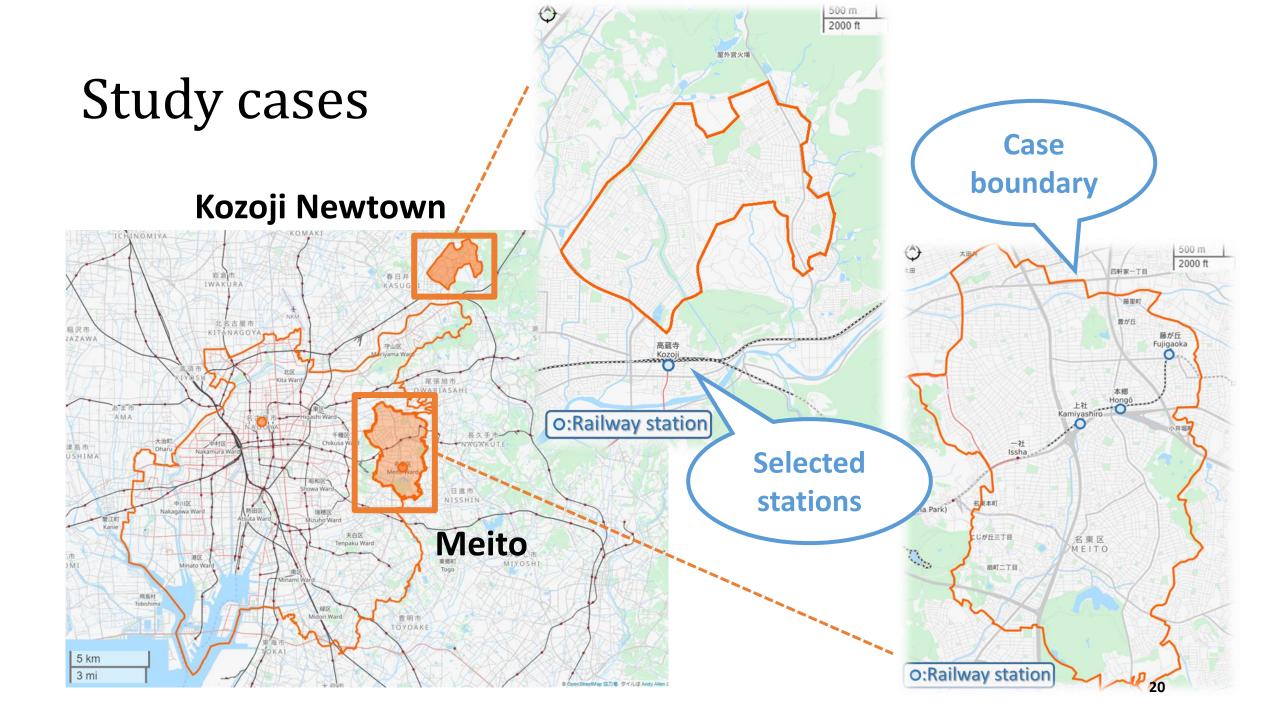
**Supply** 











#### Simulation



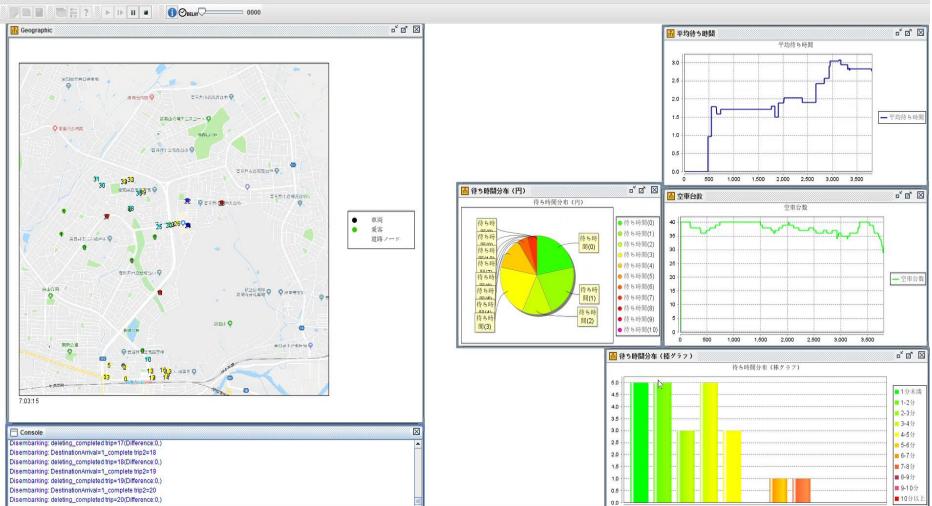


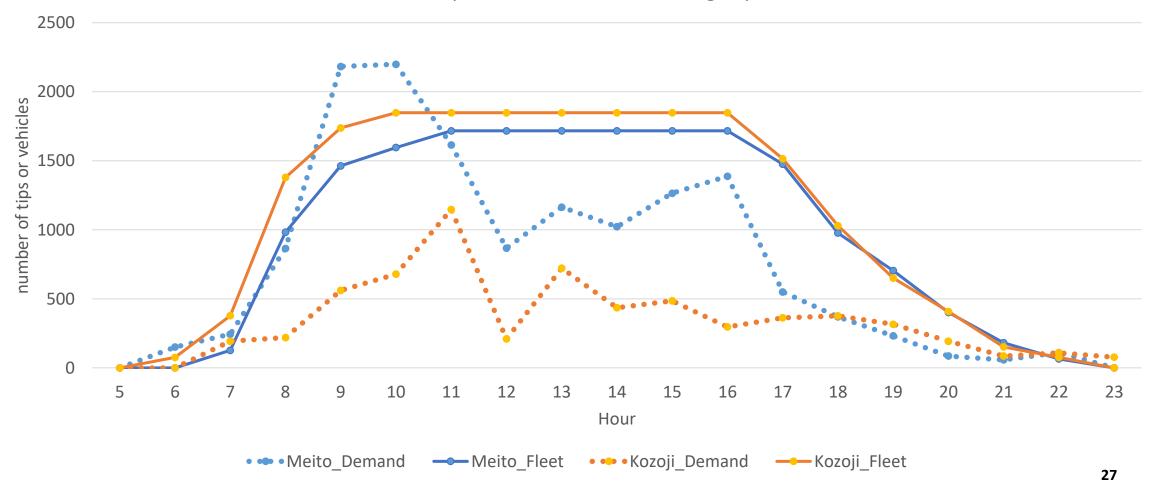
Figure 5. Interface of agent-based simulation (source: artisoc)

# P&R combined SAV system

- Background
- Objective
- Simulation
- Results
- Conclusion and limitation

#### Results —Demand and supply during daytime

Demand trips and 100% fleet size during day time



### Results —Operation Ratio

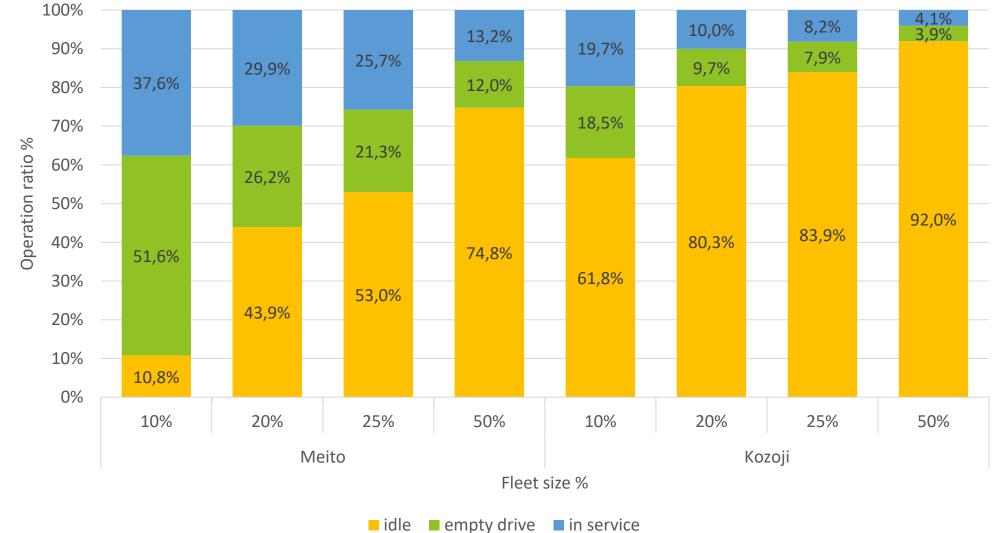


Figure. Operation ratio of Meito's various fleets

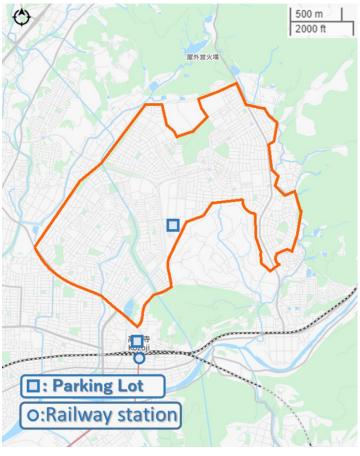


#### Ride-sharing Electric Autonomous Vehicle System

- Background
- Objective
- System & Study cases
- Simulation
- Results and conclusion

#### Study Cases —Charging Scenario 1: base case Meito Kozoji-Newtown

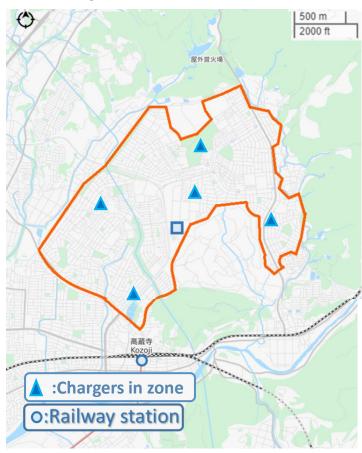




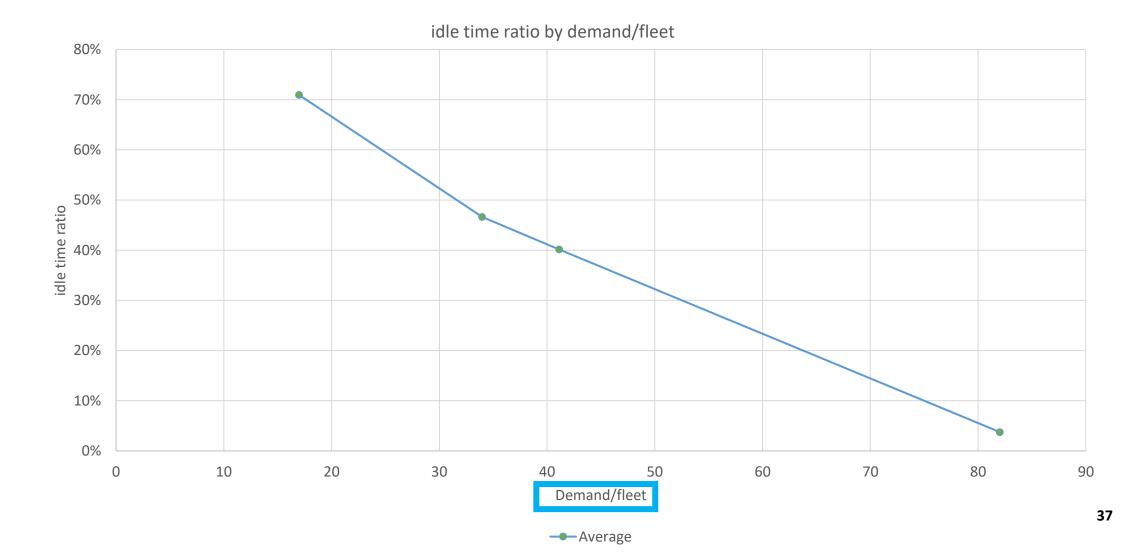
#### Study Cases —Charging Scenario 2: additional chargers Meito Kozoji-Newtown



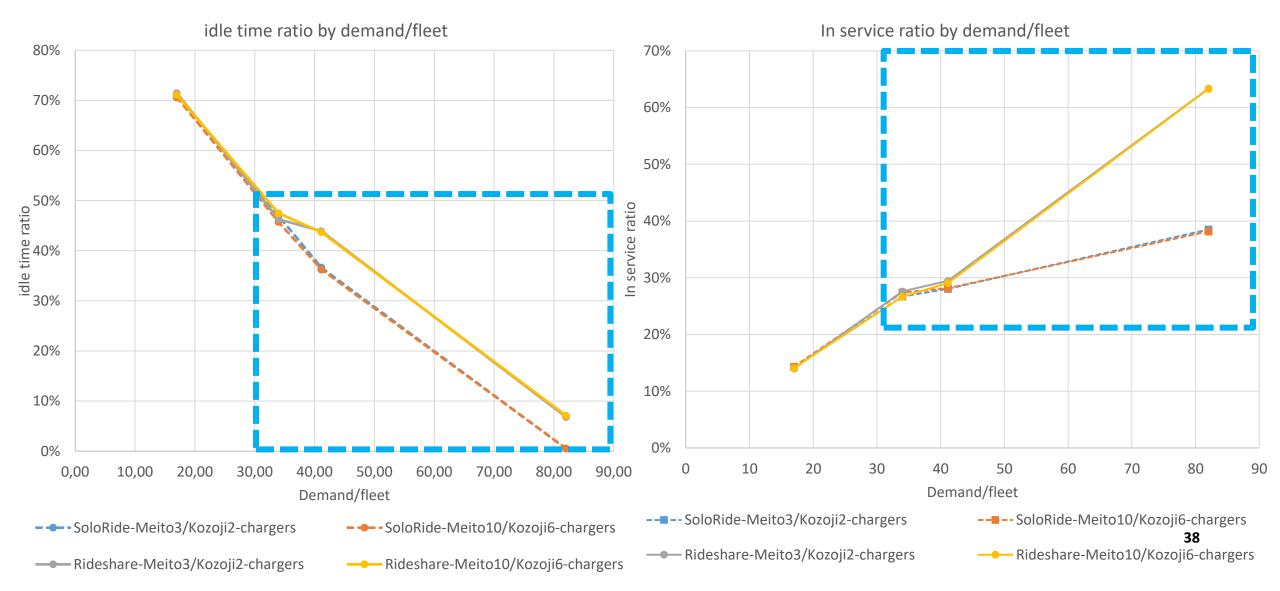
10 chargers



#### Results: Idle ratio by demand per vehicle



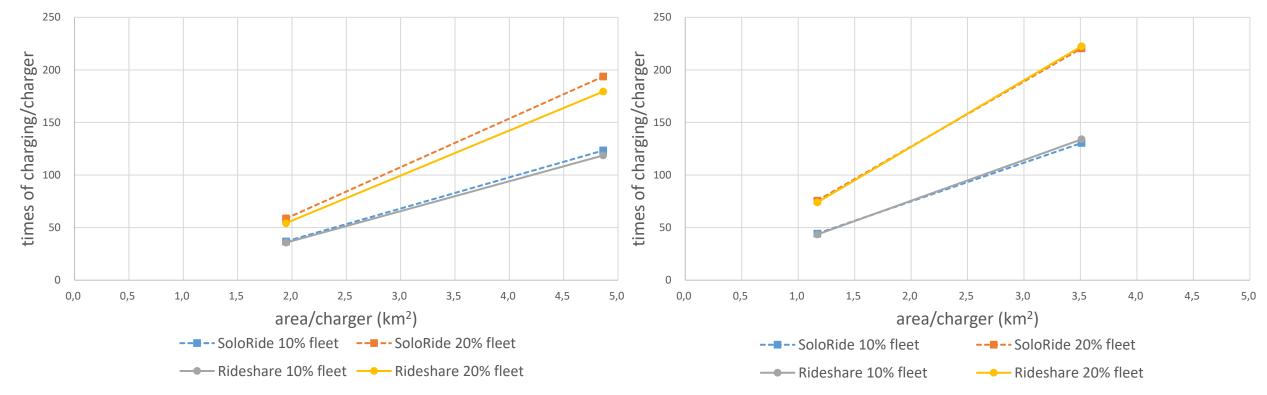
#### Results: idle, utilized time ratio



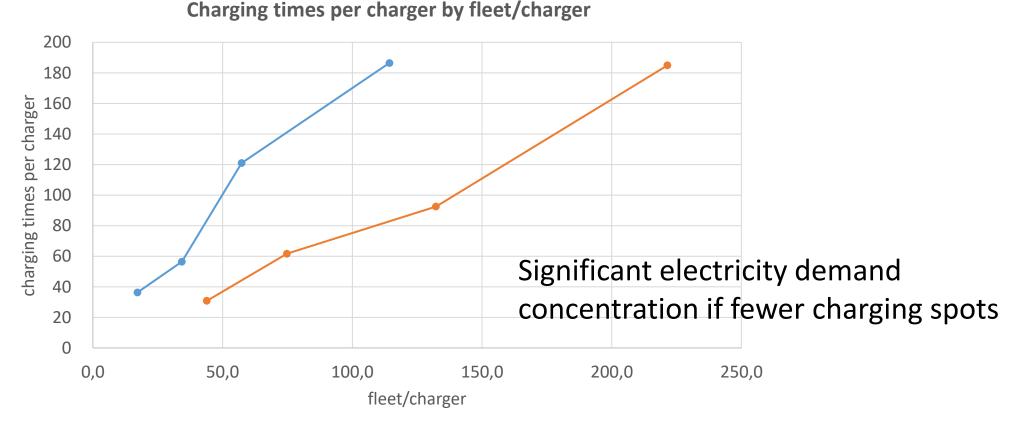
# Results: times of charging by charger coverage

Times of charging per charger by charger coverage in Meito





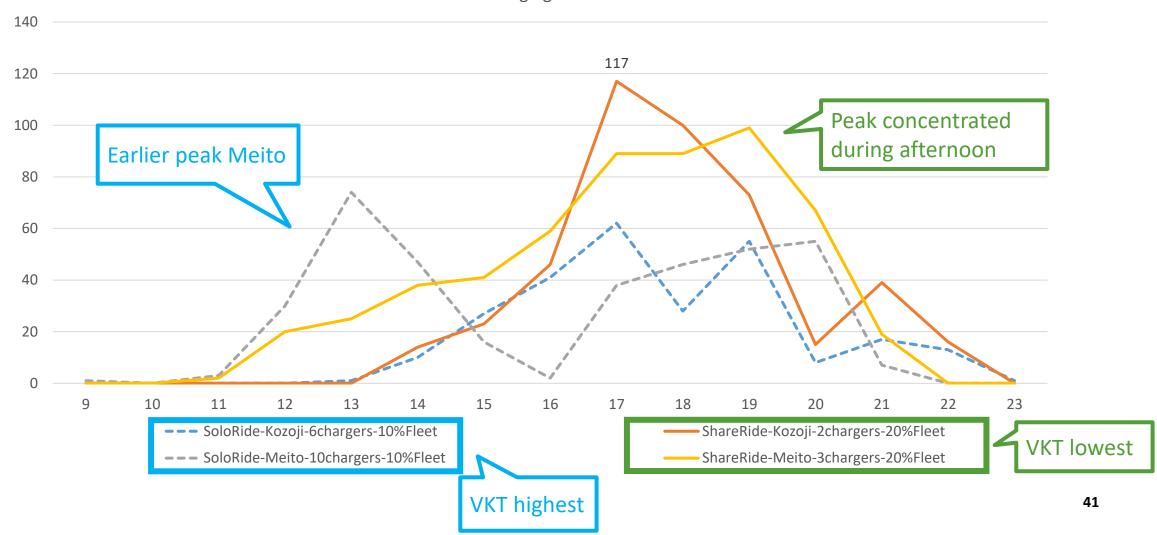
## Results: times of charging by charger coverage fleet/charger



---Meito ---Kozoji

#### Results: charging performance

Times of charging from 9 to 23



#### Conclusion —P&R SAV system: case & implication

- Meito: 20% to 25% fleet, about 400 vehicles, can provide a quick response service for over 10000
  - average wait time: about 2 min;

- Kozoji Newtown: fewer than 400 shared AVs can perform more than 6000 trips, with wait time:
  - approximately 95% of trips  $\rightarrow$  less than 6 min,
  - all trips  $\rightarrow$  approximately 1 min as an average

### Conclusion —SAEV system: overall

- The **proposed system is capable** of providing users with an acceptable service in two cases.
- Potential correlations:
  - demand per vehicle
    - the higher demand per vehicle, the higher completed trips/vehicle·hour
    - ratio of utilized time increases while idle time decreases
    - VKT also rises
  - charger coverage
    - Times of charging per charger increase with higher charger coverage
    - Electricity demand concentration